Lesson Plan

Name of the Faculty	:	Dr. Rajender Kumar Tayal
Discipline	:	Mechanical Engineering
Semester	:	5 th
Subject	:	Theory of Machines (TOM)
Lesson Plan duration	:	15 weeks (01.09.2023 to 15.12.2023)
Work load per week	:	Lecture – 03, Practical – 02

Week	Theory			EXECUTION		
	Lecture	Topic (Including assessment/test)	Date	Sign.		
1 st	Day 1 st					
1	1	Introduction about the subject and brief overview.				
	2^{nd}	1 Simple Mechanisms:				
		1.1 Kinematics of Machines: - Definition of Kinematics,				
		Dynamics, Statics, Kinetics, Kinematic link, Kinematic Pair				
		and its types				
	3 rd	1.1 Constrained motion and its types, Kinematic chain and its				
- nd	th	types				
2^{nd}	4 th	1.1 Mechanism, inversion, machine and structure.				
		1.2 Inversions of Kinematic Chain: Inversion of four bar				
	41-	chain, coupled wheels of Locomotive & Pantograph.				
	5^{th}	1.2 Inversion of Single Slider Crank chain- Rotary I.C.				
		Engines mechanism, Crank and Slotted lever quick return				
		mechanism. 1.2 Inversion of Double Slider Crank Chain- Scotch Yoke				
	6^{th}					
		Mechanism & Oldham's Coupling.				
3 rd	$7^{\rm th}$	2 Power Transmission:				
		2.1 Introduction to Belt and Rope drives.				
		2.2 Types of belt drives.				
	8^{th}					
		transmitted, centrifugal tension, and condition for maximum				
		horse power (simple numericals)				
	9 th	2.4 (simple numericals)				
4 th	10 th	2.5 Different types of chains and their terminology				
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	11 th	2.6 Gear Drive - Simple, compound, reverted and epicyclic				
	12^{th}	gear trains (simple numericals) 2.7 Relative advantages and disadvantages of various drives				

4]-	4-		
5 th	13 th	3. Flywheel:	
		3.1 Principle and applications of flywheel	
	14^{th}	3.2 Turning - moment diagram of flywheel for different	
		engines.	
	15 th	3.3 Fluctuation of speed and fluctuation of energy - Concept	
		only.	
6 th	16 th	3.4 Coefficient of fluctuation of speed and coefficient of	
_	_	fluctuation of energy.	
	17^{th}	1 st sessional test (Tentative)	
	17		
	18 th	Assessment	
	10		
7 th	19 th	4. Governor:	
/	19	4.1 Function of a governor, comparison of flywheel and	
	20 th	governor. 4.2 Simple description and working of Watt governor,	
	20	4.2 Shiple description and working of wate governor,	
	21 st	4.2 Simple description and medicing of Destances	
	21	4.2 Simple description and working of Porter governor,	
8 th	22 nd		
8	22	4.2 Simple description and working of Hartnel governor,	
	aard		
	$23^{\rm rd}$	4.2 Simple numerical based on watt and porter governor	
	th		
	24 th	4.3 Terminology used in governors: Height, equilibrium	
		speed, hunting, isochronism, stability, sensitiveness of a	
		governor.	
9 th	25 th	5. Cams:	
		5.1 Definition and function of cam. Description of different	
		types of cams and followers with simple line diagram.	
	26 th	5.2 Terminology of cam profile.	
	5.3 Displacement diagram for uniform velocity.		
	27 th	5.3 Displacement diagram for S.H.M.	
10 th	28^{th}	5.3 Displacement diagram for uniform acceleration and	
		deceleration.	
	29 th	2 nd sessional test (Tentative)	
	30 th	Assessment	
11^{th}	31 st	6. Balancing:	
		6.1 Need of balancing, Concept of static and dynamic	
		balancing.	
	32 nd	6.1 Need of balancing, Concept of static and dynamic	
		balancing.	
	33 rd	6.2 Introduction to balancing of rotating masses in the same	
		plane and different Planes (simple numericals)	
12 th	34 th	6.2 Introduction to balancing of rotating masses in the same	
14	51	plane and different Planes (simple numericals)	
	35 th	6.2 Introduction to balancing of rotating masses in the same	
	55	plane and different Planes (simple numericals)	
		Plane and anterent Planes (simple numericalis)	

	36 th	6.2 Introduction to balancing of rotating masses in the same	
		plane and different Planes (simple numericals)	
13 th	37 th	7. Vibrations:	
		7.1 Causes of vibrations in machines, Their harmful effects	
		and remedies	
	38 th	7.2 Types-longitudinal, transverse and torsional vibrations.	
	39 th	7.2 Types-longitudinal, transverse and torsional vibrations.	
14 th	40 th	7.3 Damping of vibrations	
	41 st	3 rd sessional test (Tentative)	
	42 nd	Assessment	
15 th	43 rd	Revision	
	44 th	Revision	
	45 th	Revision	

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Week		Practical	EXECUTION			
	Practical Day 1 st	Торіс	G1	G2	Sign.	
1 st	1 st	Introduction about the Lab & brief discussion over the Lab practical's to be conducted.				
2 nd	2 nd	1. To study inversion of Four Bar Mechanism, Single Slider Crank Chain Mechanism and Double Slider Crank Chain Mechanism with the help of working models.				
3 rd	3 rd	1. To study inversion of Four Bar Mechanism, Single Slider Crank Chain Mechanism and Double Slider Crank Chain Mechanism with the help of working models				
4 th	4 th	2. To study various kinds of belts drives and gear trains with the help of working models.				
5 th	5 th	3. To find the moment of inertia of a flywheel.				
6 th	6 th	Checking of Practical file/ 1st sessional test (Tentative)				
7 th	7 th	4. To Study the different types of centrifugal governors & to plot graph between R.P.M & Displacement.				
8 th	8 th	4. To Study the different types of centrifugal governors & to plot graph between R.P.M & Displacement.				

th	th			
9 th	9 th	5. To construct cam profile for		
		uniform velocity, SHM and uniform		
		acceleration and retardation on		
		drawing sheet.		
10^{th}	10 th	Checking of Practical file/		
		2nd sessional test (Tentative)		
11 th	11 th	5. To construct cam profile for		
		uniform velocity, SHM and uniform		
		acceleration and retardation on		
		drawing sheet.		
12^{th}	12^{th}	5. To construct cam profile for		
		uniform velocity, SHM and uniform		
		acceleration and retardation on		
		drawing sheet.		
13 th	13 th	6. To perform the experiment of		
_		Balancing of rotating parts and find		
		the unbalanced couple and forces.		
14 th	14 th	Checking of Practical file/		
		6		
		3rd sessional test (Tentative)		
15^{th}	15^{th}	Checking of Practical file/		
		Evaluation.		